

# Introduction to ML Based on First Chapter of Géron's Book

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Computational Intelligence Class

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Extra!

# \*Introduction to Jupyter notebooks



The screenshot shows a JupyterLab interface. On the left is a file browser with a search bar and a list of files and folders. The main area displays a notebook cell with the following content:

Inteligência Artificial e Aprendizado de Máquina Aplicados a Redes 5G e 6G. Aldebaro Klautau (UFPA). Minicurso 5 do SBR-T - 25 de setembro de 2022.

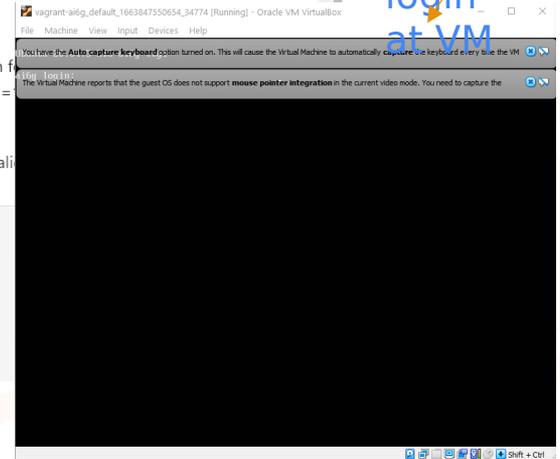
▼ Detection of QAM over AWGN using machine learning

Goals:

1. To get results as close as possible of the optimum provided by the theoretical equation for the maximum SNR. You can modify any value in this notebook, but keep the modulation order as M=4 in the context of AI/ML, such that we have 4 bits per symbol.
2. Make sure the symbol error rate (SER) estimations obtained with a test set and cross-validation are accurate.

```
[213]: # Clone the repository if running in Colab and install all the dependencies
if 'google.colab' in str(get_ipython()):
    import sys
    import os
    try:
        !git clone https://github.com/aldebaro/ai6g.git
    except:
        print("ai6g is already in the contents")
```

No need to login at VM



Extra!

# \*Introduction to Jupyter notebooks (2)



The screenshot shows a Jupyter notebook browser window. The browser address bar shows `localhost:8891/notebooks/hello_world.ipynb`. The notebook header displays "jupyter hello\_world" and "Last Checkpoint: a minute ago (unsaved changes)". The menu bar includes "File", "Edit", "View", "Insert", "Cell", "Kernel", "Widgets", and "Help". The toolbar contains icons for "Run", "Stop", "Refresh", "Undo", "Redo", "Markdown", and "Trust".

Annotations with red arrows point to the following elements:

- Header**: Points to the notebook title and status bar.
- Menu**: Points to the top menu bar.
- Toolbar**: Points to the toolbar icons.
- Code cell, press Shift + Enter to run**: Points to a code cell containing `print('Hello World')`.
- Code cell outputs**: Points to the output "Hello World" below the code cell.
- Raw Markdown cell after double click**: Points to a code cell containing raw markdown syntax:

```
1 # This is a markdown cell (header level 1)
2
3 ## Header level 2
4
5 You can use bold text
6
7 You can use bullets list:
8
9 * bullet 1
10 * bullet 2
```
- Rendered Markdown cell after pressing Shift + Enter**: Points to the rendered output of the raw markdown cell, which is formatted as:

**This is a markdown cell (header level 1)**

**Header level 2**

You can use **bold** text

You can use bullets list:

  - bullet 1
  - bullet 2

*Extra!*

# \*Jupyter shortcuts, magic and shell commands



## Two different keyboard input modes:

- **Edit** mode: type code or text into a cell.  
Green cell border
- **Command** mode: notebook level commands. Gray cell border with a blue left margin

## Shortcuts that work in both edit and command modes:

**Shift + Enter** - run the current cell, select below

**Ctrl + Enter** - run selected cells

**Alt + Enter** - run the current cell, insert below

**Ctrl + S** - save and checkpoint

560

## Magic commands:

`%matplotlib inline` - **Display matplotlib graphs in notebook**

`%run <file name>` - **Run a file**

`%%time` - **Get an execution time**

`%who` - **List all variables**

`%pinfo <variable>` - **Get detailed information about variable**

`%env` - **List all environment variables**

`%load_ext autoreload` - **Reload modules**

`%pip` - **Install in current kernel (instead**

## Shell commands in IPython / Jupyter:

Use the `!` character as prefix to the command.

For instance:

`!ls` (on Linux)

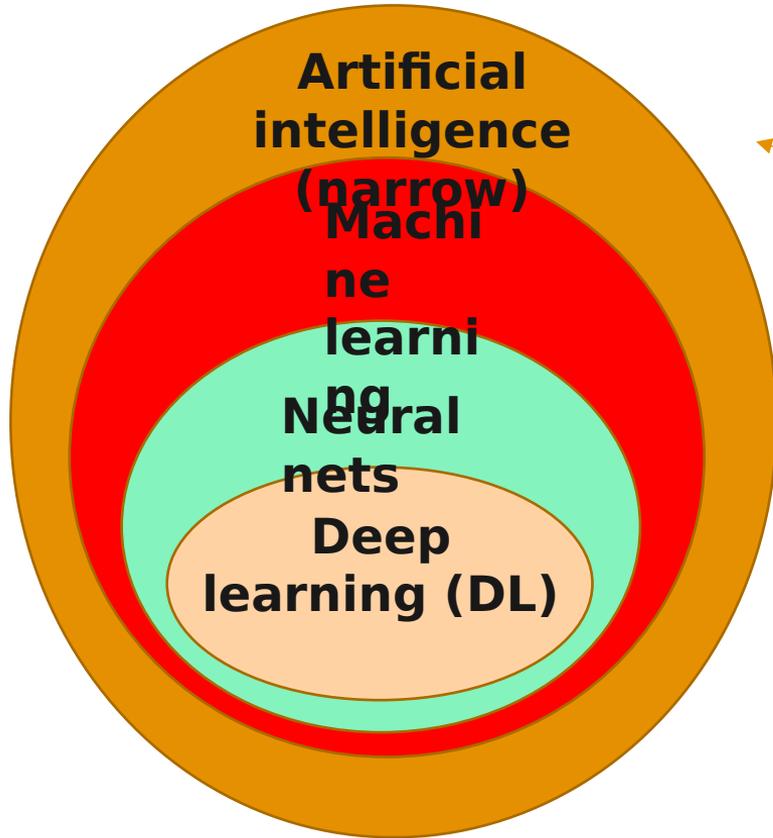
`!dir` (on Windows)

[1]

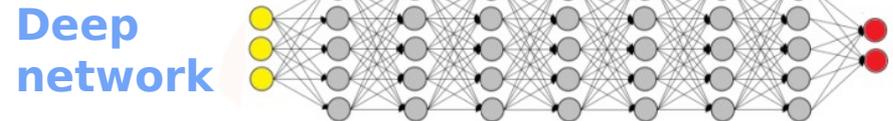
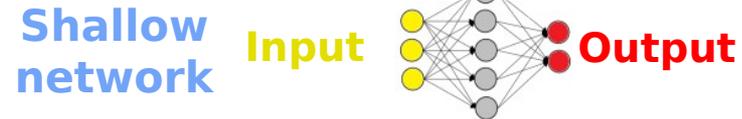
[2]

[3] <https://jakevdp.github.io/PythonDataScienceHandbook/01.05-ipython-and-shell-commands.html>

# AI, Machine Learning and Deep learning (DL)



DL is a set of techniques to **train** and **deploy** neural networks with large number parameters



*Extra!*

# \*Classification and regression problems



- Both rely on **supervised learning**: when training the model, we know the correct **output  $y$**
- The **input** is a vector  $x=[x_1, \dots, x_N]$  with  $N$  **features**

Difference

S:

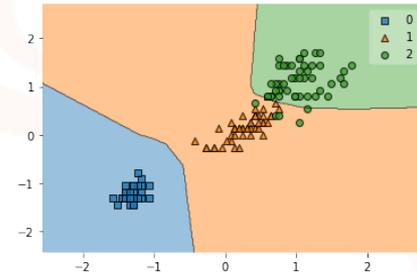
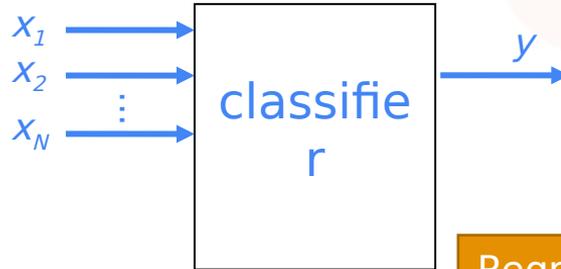
Classification

- Output  $y$  is an element of a set  $\{1, \dots, Y\}$  of  $Y$  labels.
- Evaluation is based e.g. on misclassification (or error)

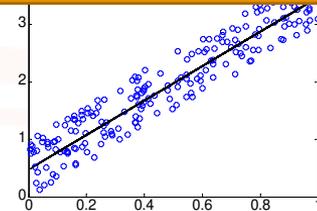
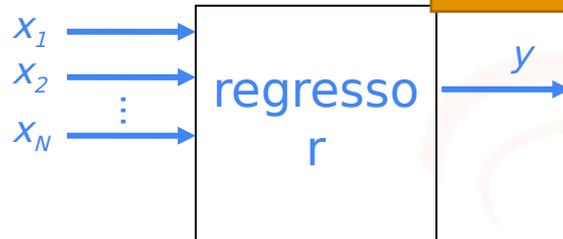
Regression

- Output  $y$  is a real number or vector (multivariate regression)
- Evaluation is based e.g. on the mean-squared error (MSE), mean absolute error

Classification example: input  $[x_1, x_2]$ ,  $N=2$  and



Regression example: input  $x_1$ ,  $N=1$  and

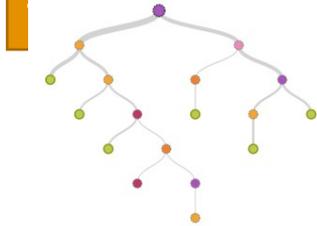


# Learning algorithms (most support classification and regression)

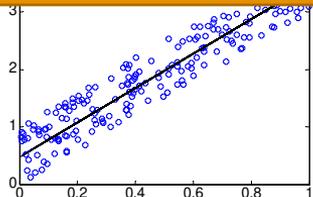
Decision stump (single if/else rule)



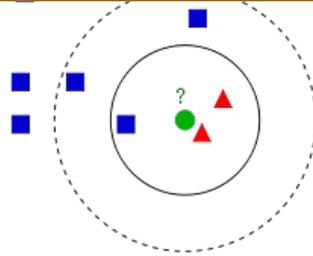
Decision



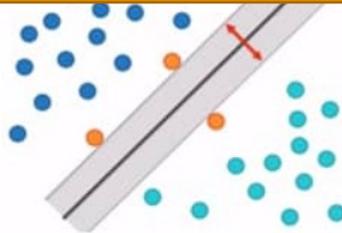
Linear regression



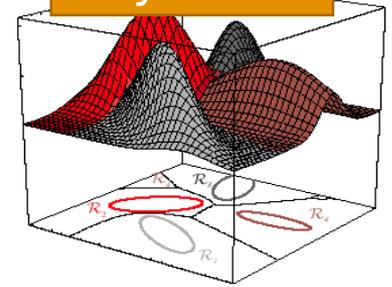
K-nearest neighbors  
(KNN)



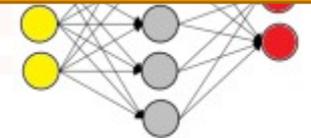
Support vector machine  
(SVM)



Naïve Bayes

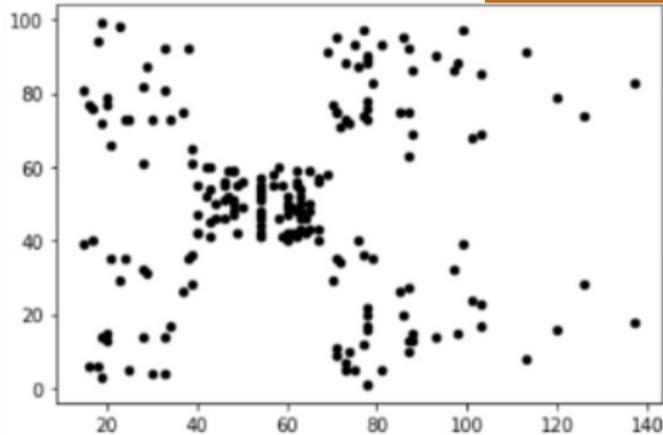


Artificial neural network  
(ANN)

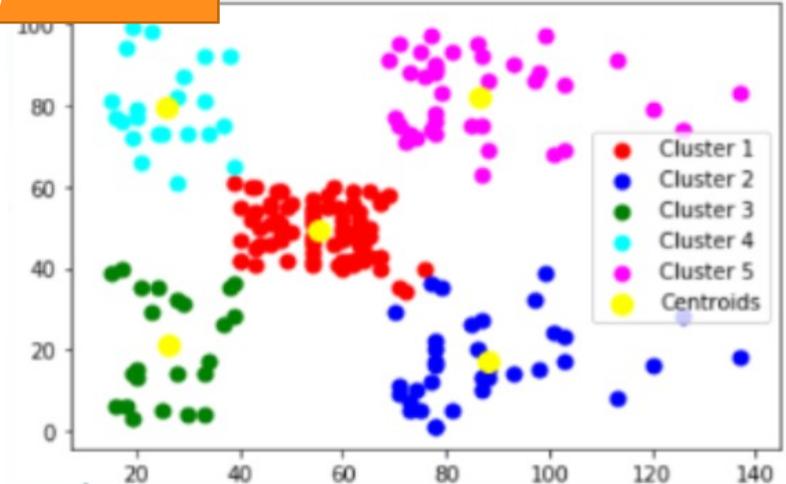


# Alternative to supervised learning: unsupervised

## Unsupervised learning



Unlabeled data



K-means clustering with K=5 centroids

## Popular special case of unsupervised learning: anomaly detection

### Examples of anomalies (univariate time series)



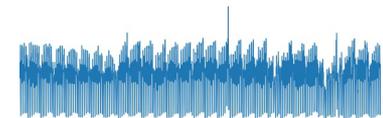
Spike



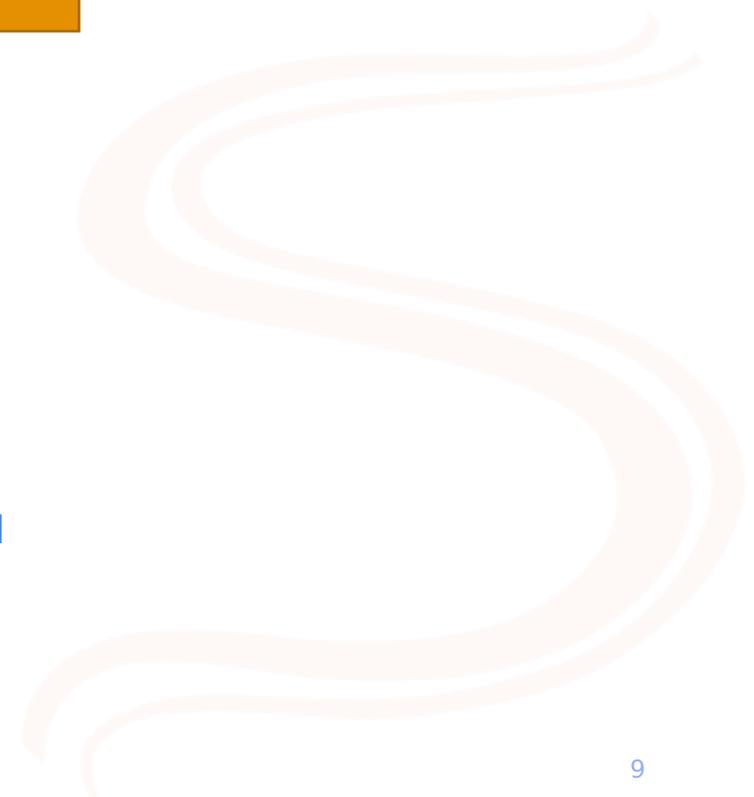
Level  
shift



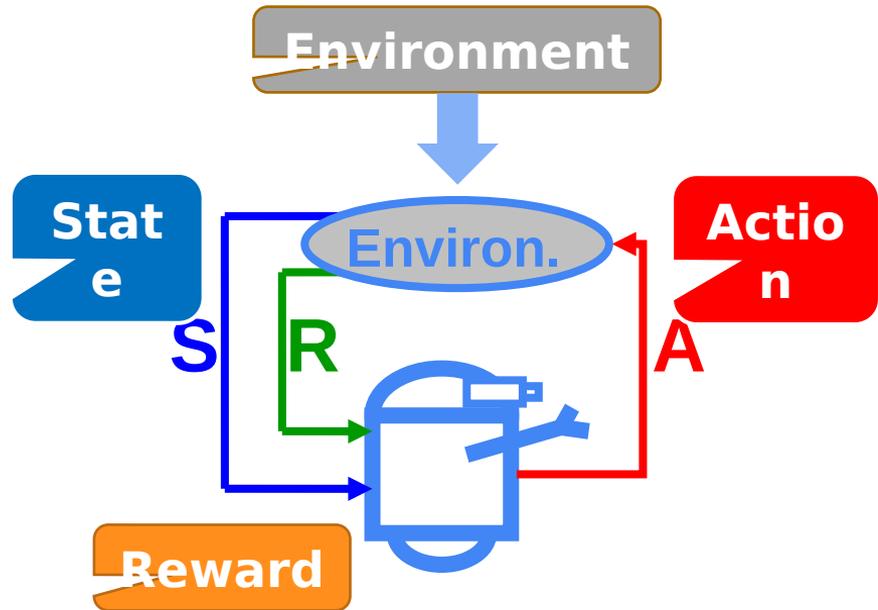
Pattern  
change



Anomal  
y in  
season  
al  
pattern  
s



# Distinct from supervised and unsupervised learning: Reinforcement Learning (RL)



Online learning, no need for output labels.  
Support to delayed reward

Goal: Find a policy that maximizes the return over a lifetime (episode, if not a continuing task), not the immediate reward

# Classification with Scikit-Learn

# Simple classifiers (for two simple sets)

Let us design a decision stump using the two simple sets below:

## Training set

Length	Weight	Class $y$
12	3.2	0
10	0.5	1
14	2.8	0
14	2.4	0
13	1.8	1
13.8	1.5	0
11	1	1

## Test set

Length	Weight	Class $y$
13	3.1	0
9	0.8	0
12.3	1.4	1
10	2.3	1



# First classifier: decision stump

Decision stump is a single if / else rule based on a chosen threshold value of a chosen feature

First example:

if weight > 1

then class label is 0

This gives one error in training set!

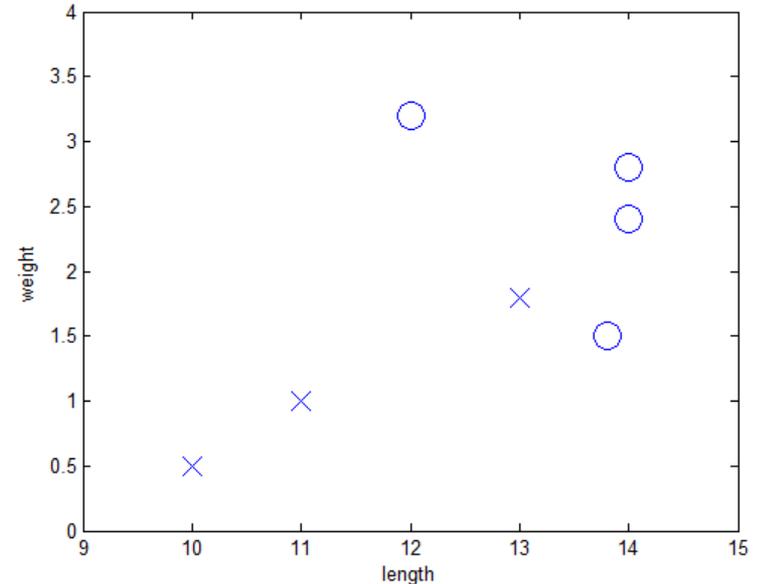
Another example:

if length < 12

then class label is 1

This also gives one error in training set!

Arquivo	Editar	Formatar	Exibir	Ajuda
12		3.2		0
10		0.5		1
14		2.8		0
14		2.4		0
13		1.8		1
13.8		1.5		0
11		1		1



# Test our decision stump

Example:

If  $\text{weight} > 1$

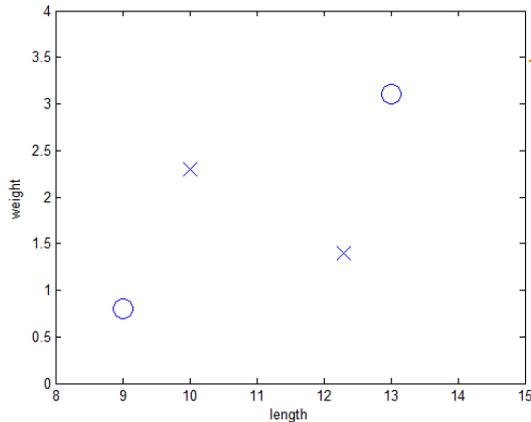
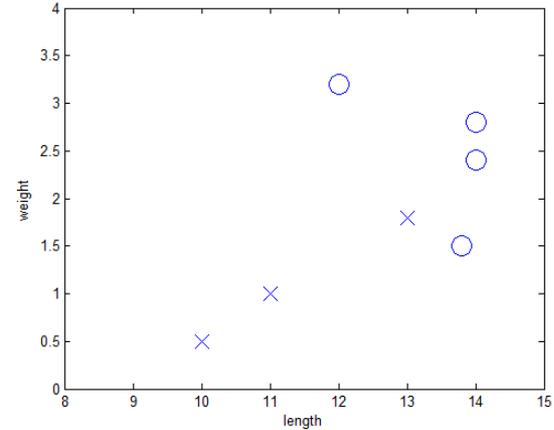
then class label is 0

Else

then class label is 1

This gives one error in training set!

But gives three errors in this (strange) test set!



test\_set.txt - Bloco de n...

Arquivo	Editar	Formatar	Exibir	Ajuda
13	3.1	0		
9	0.8	0		
12.3	1.4	1		
10	2.3	1		

# Another dataset: Iris

Iris has three classes with 50 examples of each class, and four input features: width and length for petal and sepal

**iris setosa**



petal

sepal

**iris versicolor**



petal

sepal

**iris virginica**

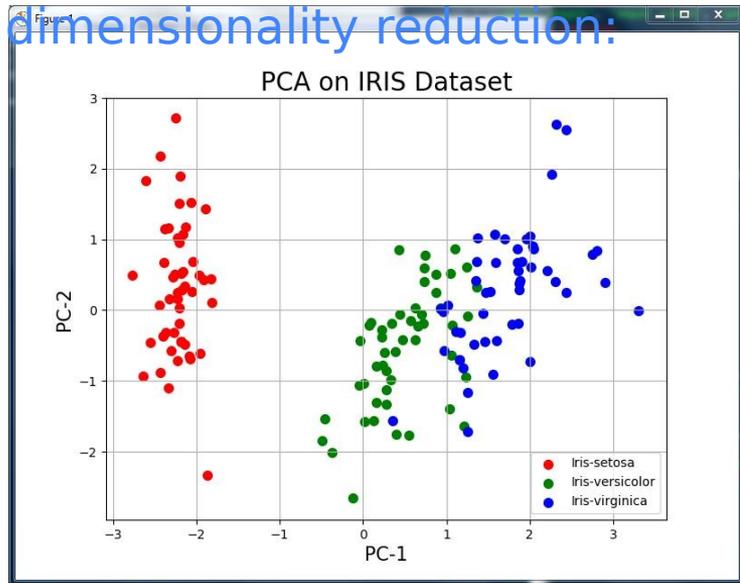


petal

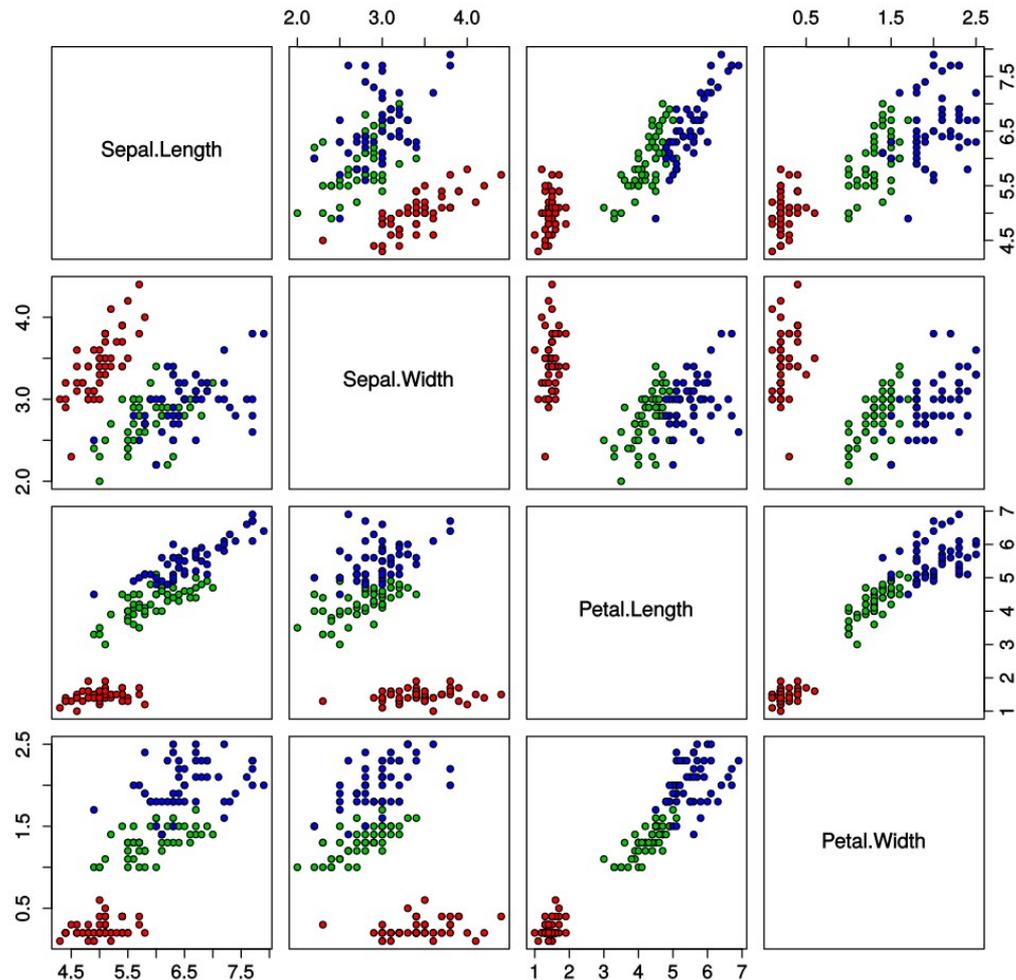
sepal

# Iris

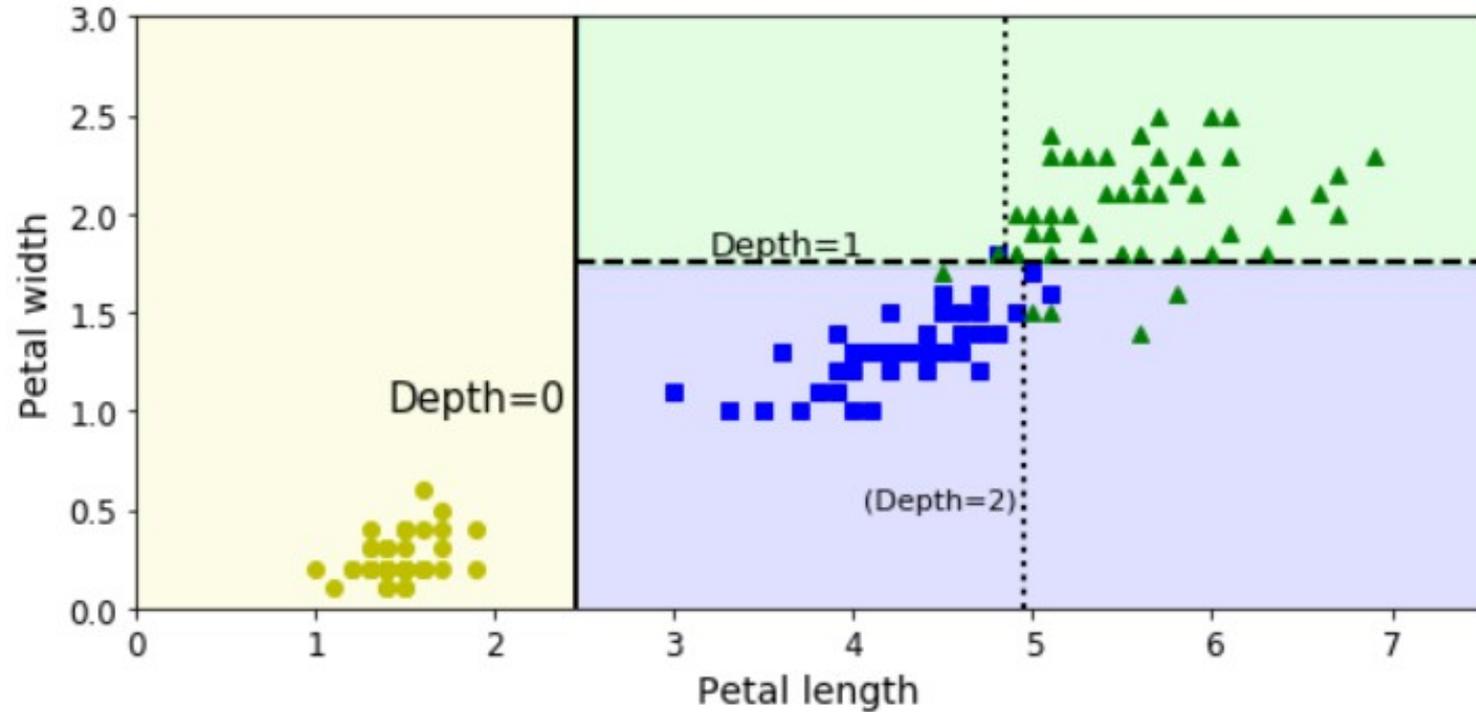
Principal component analysis (PCA) for dimensionality reduction:



Iris Data (red=setosa,green=versicolor,blue=virginica)



# Exemplo: Dataset Iris



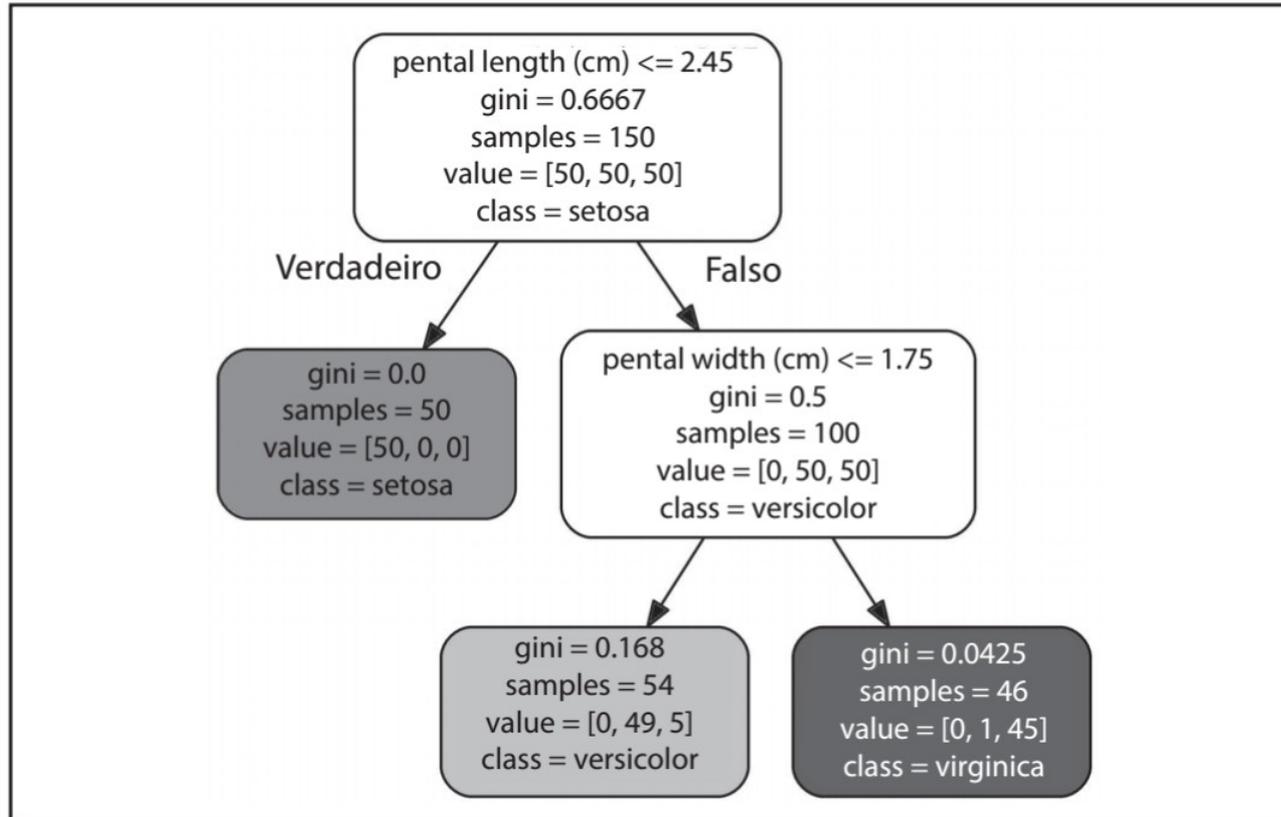
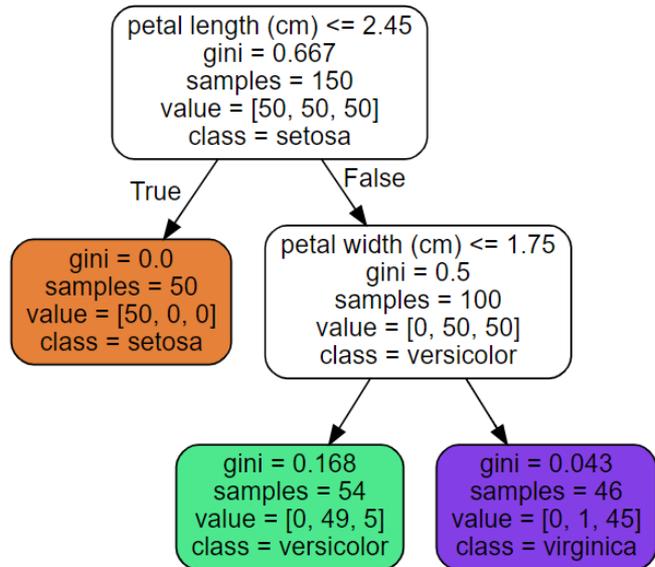
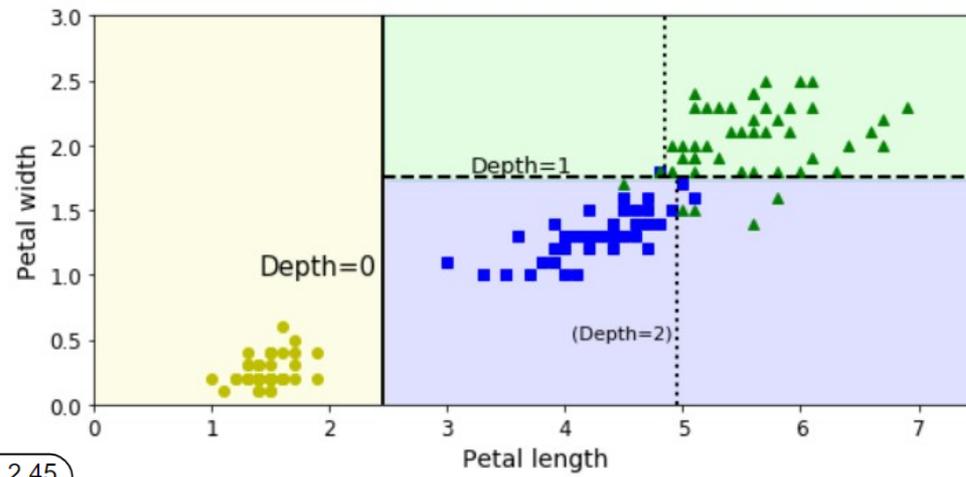
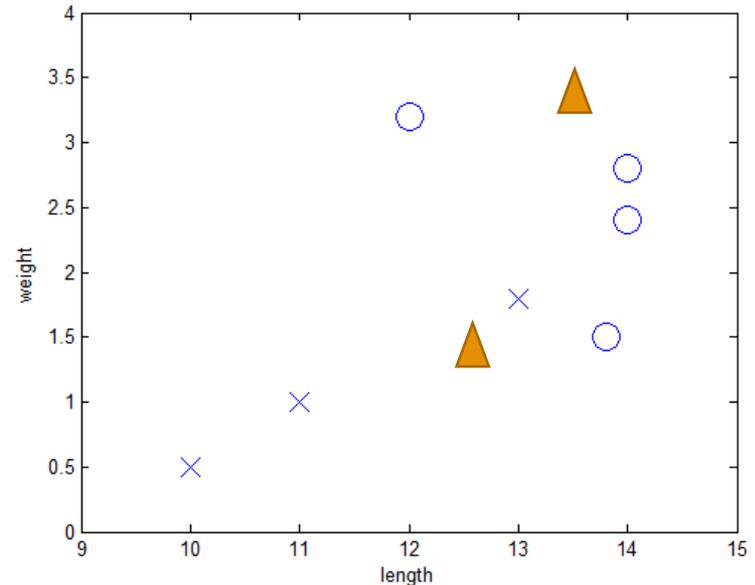


Figura 6-1. Árvore de Decisão da íris



# Nearest neighbor classifier

- ↳ The nearest neighbor (NN) classifier simply stores the whole training sequence and, according to the adopted distance measure (e.g. Euclidean distance) assigns to the test example the same class of its nearest (smallest distance) neighbor (example of the stored training sequence)
- ↳ The Euclidean distance corresponds to the squared value of the error vector norm
  - ↳  $y$  represents the test vector
  - ↳  $z$  represents a training example
  - ↳ Euclidean:  $\text{distance}(y, z) = \|y - z\|^2$

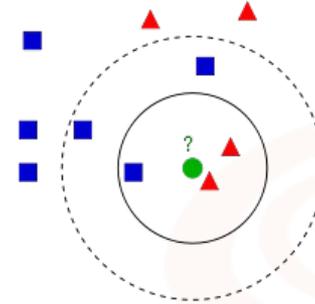


# Generalizing the NN: K-nearest neighbors

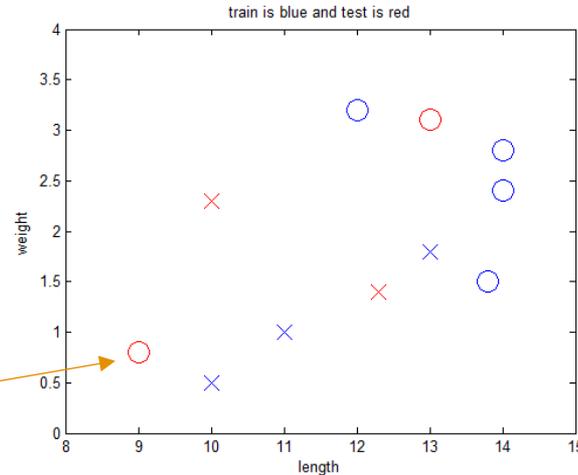
↳ KNN classifier: choose  $K$  as an integer odd number (e.g.  $K=3$  or  $5$  is widely adopted) and make the classifier to output the most popular label among the  $K$  nearest neighbor as final decision

↳ The previous NN classifier is equivalent to using  $K=1$ , which may be less robust to *outliers* than  $K > 1$

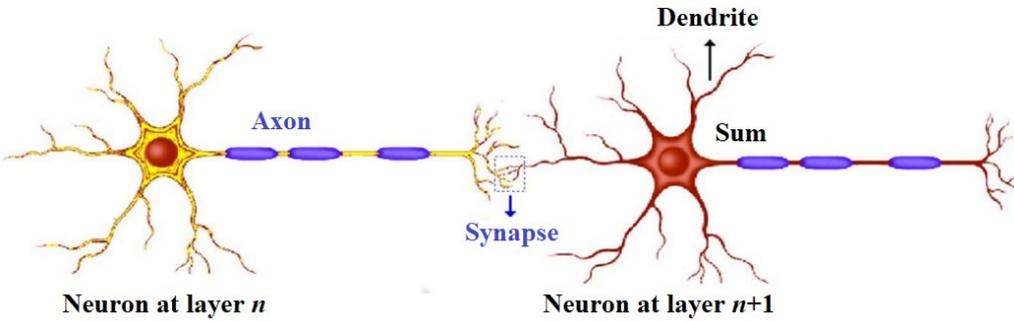
↳ Example: assume that all red and blue examples compose a new training sequence. Note the outlier!



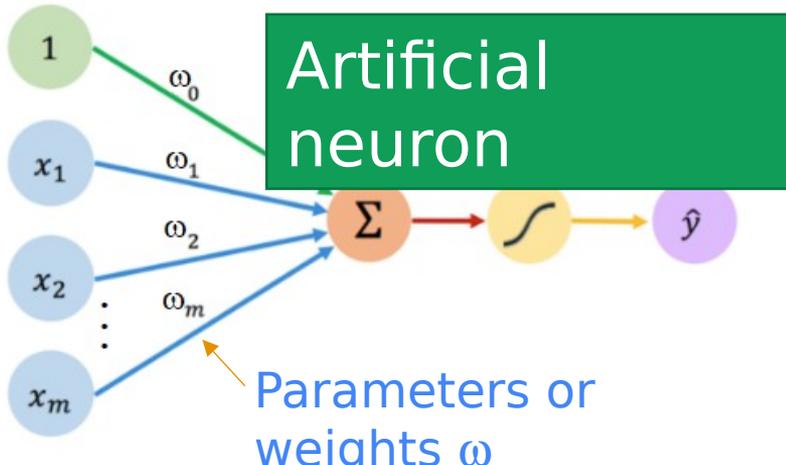
Example from Wikipedia  
[en.wikipedia.org/wiki/K-nearest\\_neighbors\\_algorithm](https://en.wikipedia.org/wiki/K-nearest_neighbors_algorithm)



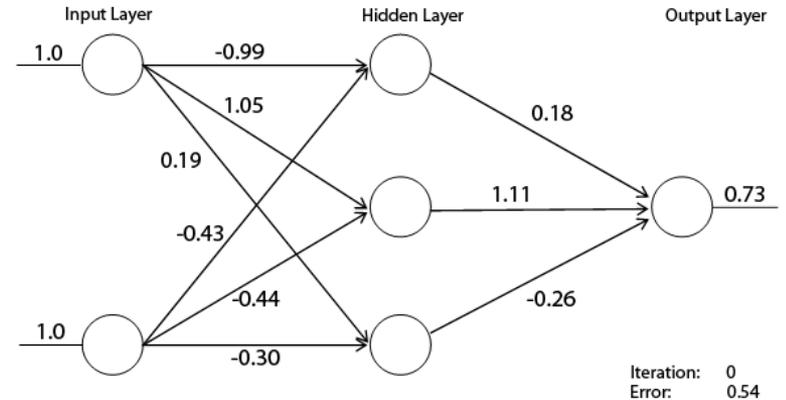
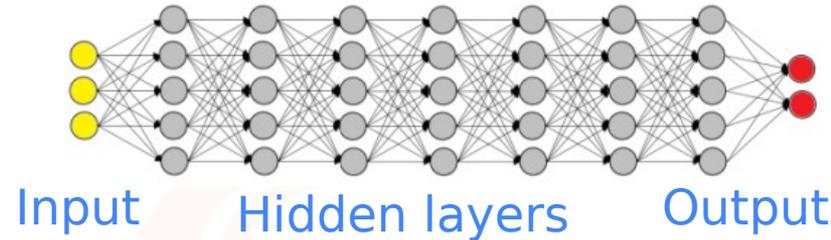
# Biological neuron



Propagation of nerve impulse



# Artificial neural network (ANN or NN)



Many layers and architectures in DL: dense (fully-connected), convolutional, recurrent, etc.

# There is life outside the deep neural net world!

*dmlc*  
**XGBoost**

<https://dmlc.github.io>

<https://xgboost.ai>

**XGBoost** is an optimized distributed gradient boosting library designed to be highly **efficient**, **flexible** and **portable**. It implements machine learning algorithms under the **Gradient Boosting** framework. The same code runs on major distributed environment (Hadoop, SGE, MPI) and can solve problems beyond billions of examples.

# \*Random forest: ensemble of decision trees

*Extra!*

Meta-algorithms

Bagging

Base learners

Decision trees

Random forest: model composed of  $T$  decision trees ("estimators" in sklearn)

Recipe:

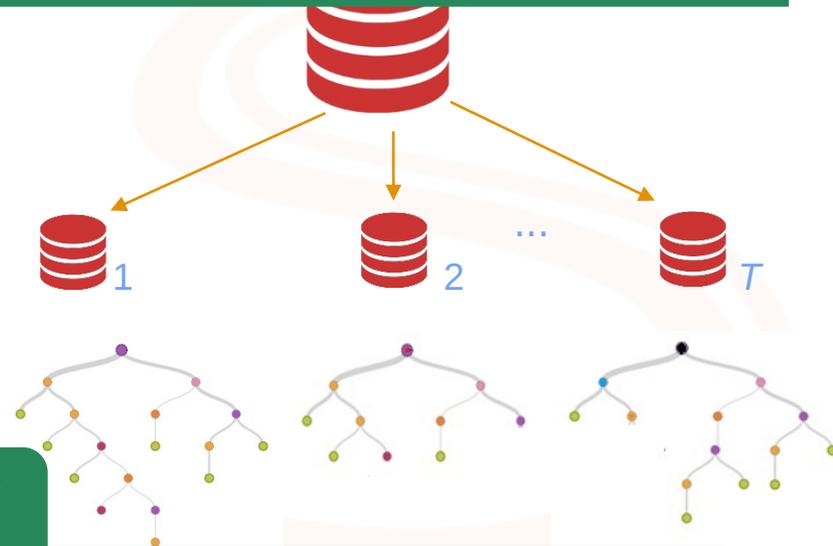
Use decision trees to create a random forest

Bootstrap (sample with replacement)

Random features subsets

Final classification result by voting

Fast training and good generalization. State-of-art results for tabular data



# Scikit-learn algorithms for classification



Relevant hyperparameters

Decision tree:

```
DecisionTreeClassifier(min_samples_leaf=5)
```

Decision stump:

```
DecisionTreeClassifier(max_depth=1)
```

Naive Bayes

```
GaussianNB(priors=None, var_smoothing=1e-09)
```

K-nearest neighbors (KNN)

```
KNeighborsClassifier(n_neighbors=3, metric='euclidean')
```

Support vector machine (SVM)

```
SVC(C=1.0, kernel='rbf', decision_function_shape='ovo')
```

Linear (SVM)

```
LinearSVC(C=1.0, decision_function_shape='ovr')
```

Artificial neural network (ANN)

```
MLPClassifier(max_iter=500, hidden_layer_sizes=(100,))
```

Adaboost

```
AdaBoostClassifier(base_estimator=DecisionTreeClassifier(max_depth=1), n_estimators=50)
```

Random forest

```
RandomForestClassifier(n_estimators=30, max_depth=100)
```

# Classification with scikit-learn



```
classifier = DecisionTreeClassifier(max_depth=20) #single tree
classifier = RandomForestClassifier(n_estimators=30,max_depth=10) #30 trees
classifier = SVC(gamma=1, C=1) #SVM with RBF kernel

classifier.fit(X_train, y_train) #training stage
y_predicted = classifier.predict(X_test) #test stage
print('Accuracy = ', accuracy_score(y_test, y_predicted))
```

Be aware that modern ML has sophisticated workflows that require time to set up and get familiar with

# Tipo de treino

A solid blue circle containing the text 'Classificação'.

Classificação

A light gray circle with a thick red border containing the text 'Regressão'.

Regressão

# Métricas de performance

instâncias  
Ex: casa

*Equation 2-1. Root Mean Square Error (RMSE)*

$$\text{RMSE}(\mathbf{X}, h) = \sqrt{\frac{1}{m} \sum_{i=1}^m (h(\mathbf{x}^{(i)}) - y^{(i)})^2}$$

## Métricas de performance

X= Valores  
dos atributos

*Equation 2-1. Root Mean Square Error (RMSE)*

$$\text{RMSE}(\mathbf{X}, h) = \sqrt{\frac{1}{m} \sum_{i=1}^m (h(\mathbf{x}^{(i)}) - y^{(i)})^2}$$

## Métricas de performance

Y =  
Resultado  
esperado

*Equation 2-1. Root Mean Square Error (RMSE)*

$$\text{RMSE}(\mathbf{X}, h) = \sqrt{\frac{1}{m} \sum_{i=1}^m (h(\mathbf{x}^{(i)}) - y^{(i)})^2}$$

## Métricas de performance

$h =$  Função  
*machine  
learning*

*Equation 2-1. Root Mean Square Error (RMSE)*

$$\text{RMSE}(\mathbf{X}, h) = \sqrt{\frac{1}{m} \sum_{i=1}^m (h(\mathbf{x}^{(i)}) - y^{(i)})^2}$$

# Feature scaling

**Min-max**  
scaling  
(*normalization*)

**Standard**  
scaling  
(*standardization*)

# Feature scaling

## Min-max scaling (*normalization*)

- Limita o *range* para valores entre 0 e 1 (ou outro range designado)

- **Desvantagem:** sujeito a ter a performance prejudicada por outliers, ou seja, valores que estão muito acima ou muito abaixo da média

- **Método de aplicação:**

Para cada amostra

- 1) Subtrair o valor pelo valor mínimo
- 2) Dividir o valor pela diferença entre valor mínimo e máximo

Ex:  $\text{valor} - \text{min}$

# Feature scaling

- Faz com que a distribuição dos dados passe a ter média 0 e variância unitária.

- **Desvantagem:** Não está restrito a um *range* específico

- **Método de aplicação:**

Para cada amostra

- 1) Subtrair o valor pelo valor médio
- 2) Dividir o valor pelo desvio padrão

Ex: valor - média

-----  
desvio padrão

**Standard**  
scaling  
(*standardizati  
on*)

# Feature scaling

Ambos os métodos são aplicados independentemente em cada feature

Alguns métodos afetados pela escala dos valores das amostras:

- KNN
- Redes Neurais
- Regressão linear
- Regressão logística
- SVM

Alguns métodos NÃO afetados pela escala dos valores das amostras:

- Árvores de decisão (decision tree)
- Random Forest

*Extra!*

## \*Deep learning frameworks



**DL training** frameworks implement sophisticated algorithms, which use “backpropagation”, automatic differentiation and stochastic gradient descent (SGD)



&



Most used language

Facebook's / Meta's

Google's, TF versions 1 and 2, with high level Keras API

**Deployment** frameworks: facilitate pruning the models and quantizing the weights for acceleration

Qualcomm's AI Model Efficiency Toolkit

[www.tinyml.org](http://www.tinyml.org)



TorchScript, Tensorflow Lite & PyTorch Quantization



Other tools: NVIDIA, Intel, etc.

Auxiliary tools for (shallow) machine learning, debugging, assessing models and running on cloud



It may not be trivial to set up your development workflow

*Extra!*

## \*Importance of proper management of Python environments



Example:  
Keras in TF2 uses hdf5 file  
format

```
conda install  
h5py==3.7.0
```

keras folder with code that requires  
h5py:  
d:\Programs\Anaconda3\envs\ai6g\Lib\  
site-packages\h5py

```
09/11/2022 05:25 PM      3,334,144  
hdf5.dll  
09/11/2022 05:25 PM      117,760  
hdf5_hl.dll
```

Folder d:\Programs\Anaconda3\envs\  
ai6g\Lib\site-packages\keras\saving

```
00/05/2022 03:23 PM      37,436
```

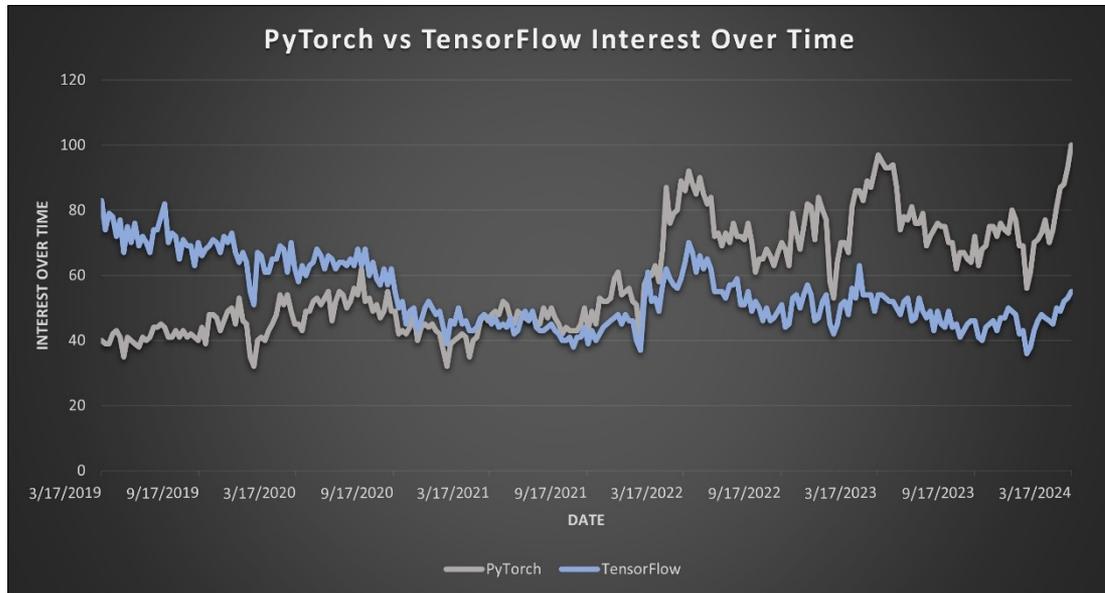
conda  
list

```
# packages in environment at d:\Programs\  
Anaconda3\envs\ai6g:  
#  
# Name                Version             Build  
Channel  
absl-py                1.2.0               pypi_0  
pypi  
aom                    3.4.0               h0e60522_1  
conda-forge  
asttokens              2.0.8               pyhd8ed1ab_0  
conda-forge  
...  
gym                    0.19.0              py39h832f523_0  
conda-forge  
h5py                    3.7.0               pypi_0  
pypi  
...  
tensorboard            2.9.1               pypi_0  
pypi  
tensorboard-data-server 0.6.1               pypi_0      pypi  
tensorboard-plugin-wit 1.8.1               pypi_0      pypi  
tensorflow              2.9.2               pypi_0
```

*Extra!*



# \*Tensorflow 2 versus Pytorch



TF2: Easier deployment to cloud, servers, mobile, and IoT devices: TensorFlow Serving and TensorFlow Lite

Pytorch: More models, for instance, at

<https://huggingface.co/>

- 85% only PyTorch
- 8% only TF
- 7% both

Tools such as:

<https://github.com/Lyken17/pytorch-OpCounter>

to count MACs / FLOPs

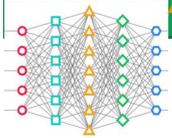
<https://levelup.gitconnected.com/why-tensorflow-for-python-is-dying-a-slow-death-ba4dafcb37e6>

<https://www.v7labs.com/blog/pytorch-vs-tensorflow>

# Model selection with a validation set

## Parameters

Values that are part of the deployed model, e.g. neural network (NN)

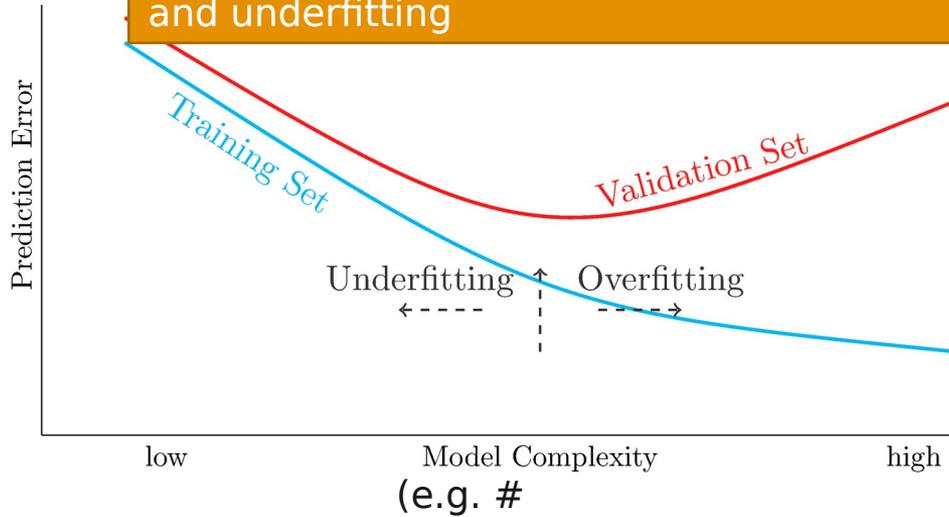


## Hyperparameters

- Model hyperparameter: e.g, topology and size of a NN
- Algorithm hyperparameters: learning rate and batch size

## Model selection

Tune hyperparameters using a validation set to avoid overfitting and underfitting



Modify hyperparameters that influence the model complexity and adopt the values that provide good performance on validation set

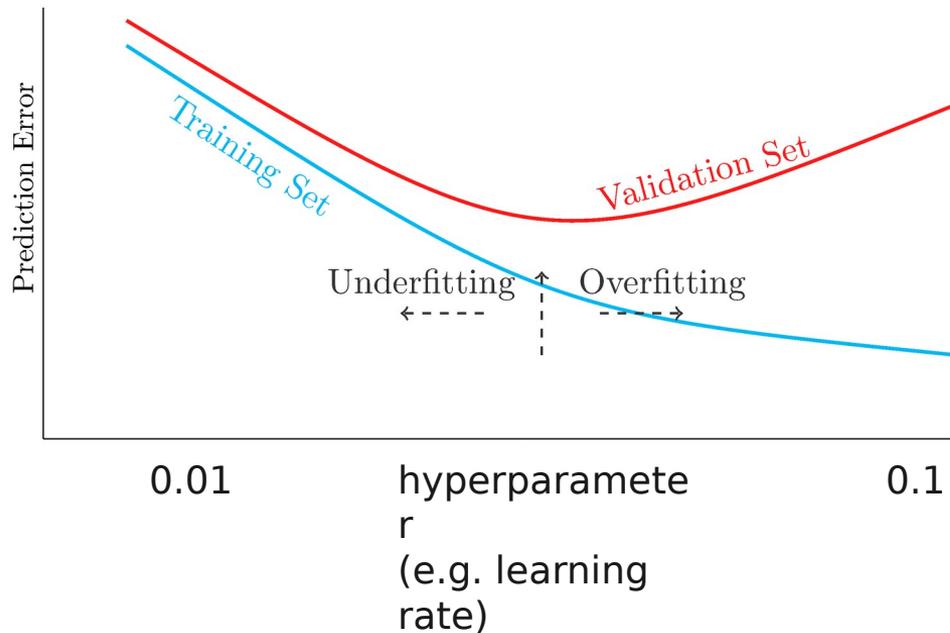
This strategy is also used to find the best value for a given hyperparameter

# Model selection with a validation set (2)

DL models have many hyperparameters!

Model selection

Tune hyperparameters using a validation set to avoid overfitting and underfitting find their best values



Some frameworks for automatic model selection:

Scikit-learn

[https://scikit-learn.org/stable/model\\_selection.html](https://scikit-learn.org/stable/model_selection.html)

Optuna

<https://optuna.org>

KerasTuner

[https://keras.io/keras\\_tuner](https://keras.io/keras_tuner)

# Early stop with a validation set

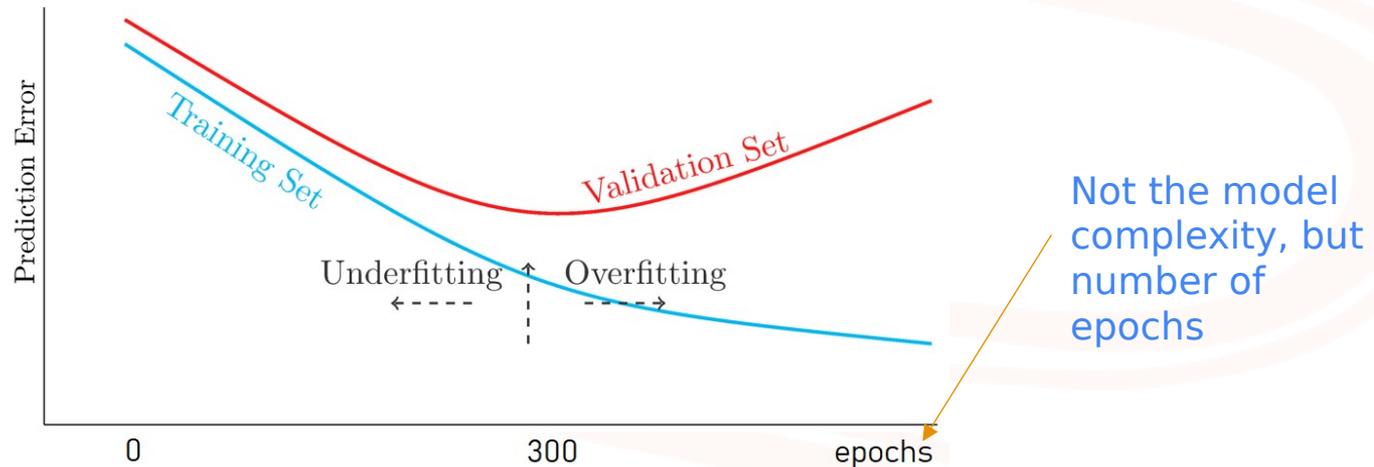


Assume model selection has indicated a set of hyperparameters

For how long should the model be trained? For how many epochs?

Epoch: one complete cycle over all training set examples that may have been shuffled

“Early stop”: interrupt training before maximum number of epochs and keep model that maximizes performance on validation set

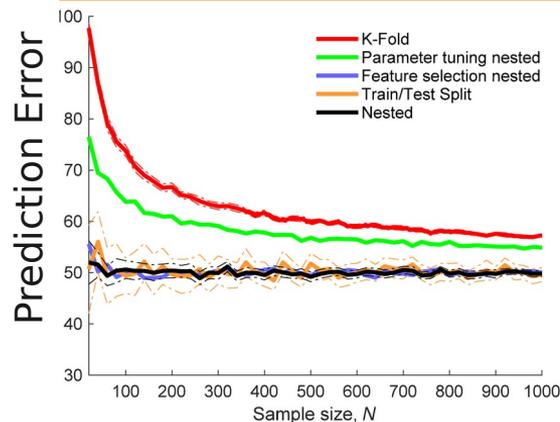
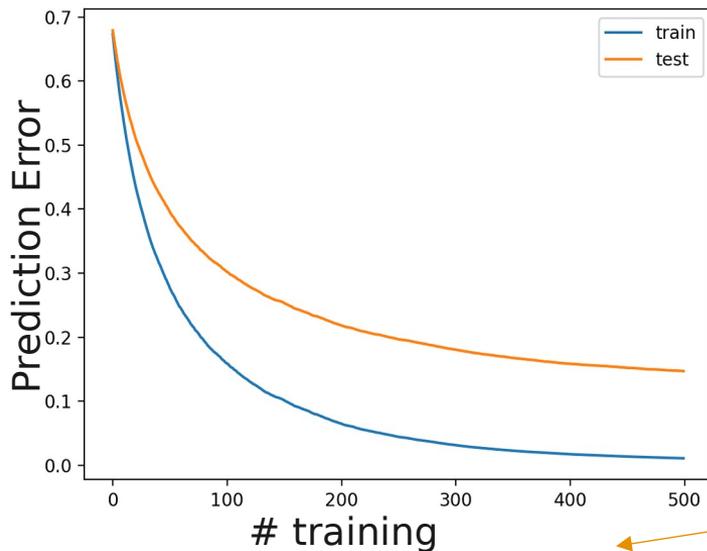


# Sample complexity

Given a set of hyperparameters and a model trained with  $N$  epochs

What is the minimum number of training examples for good performance?

The sample complexity depends on the model, hyperparameters, data, learning algorithm, etc.



[1] Machine learning algorithm validation with a limited sample size", A. Vabalas et al, 2019

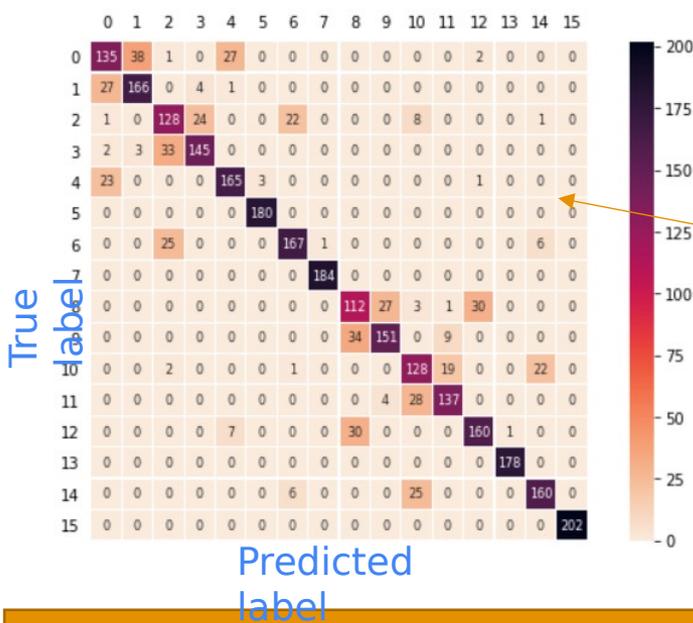
**Table 1.** The comparison on sample complexity to attain  $\epsilon$  approximate point of stability.

Algorithm	Sample complexity
REINFORCE <sup>13</sup>	$\mathcal{O}(1/\epsilon^2)$
PGT <sup>14</sup>	$\mathcal{O}(1/\epsilon^2)$
GPOMDP <sup>15</sup>	$\mathcal{O}(1/\epsilon^2)$
SVRPG <sup>4</sup>	$\mathcal{O}(1/\epsilon^{5/3})$
HAPG <sup>22</sup>	$\mathcal{O}(1/\epsilon^3)$
IS-MBPG <sup>18</sup>	$\mathcal{O}(1/\epsilon^3)$
DP-RBPG (this study)	$\mathcal{O}(1/\epsilon^3)$

[2] A randomized block policy gradient algorithm with differential privacy in Content Centric Networks, L. Wang et al, 2021.

Not the model complexity, nor the number of epochs, but the number of

# Evaluation



Confusion-matrix for classification

**Generalization error:** measure of how accurately an algorithm is able to predict outcome values for previously unseen data

Generalization error estimates:

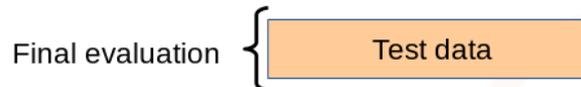
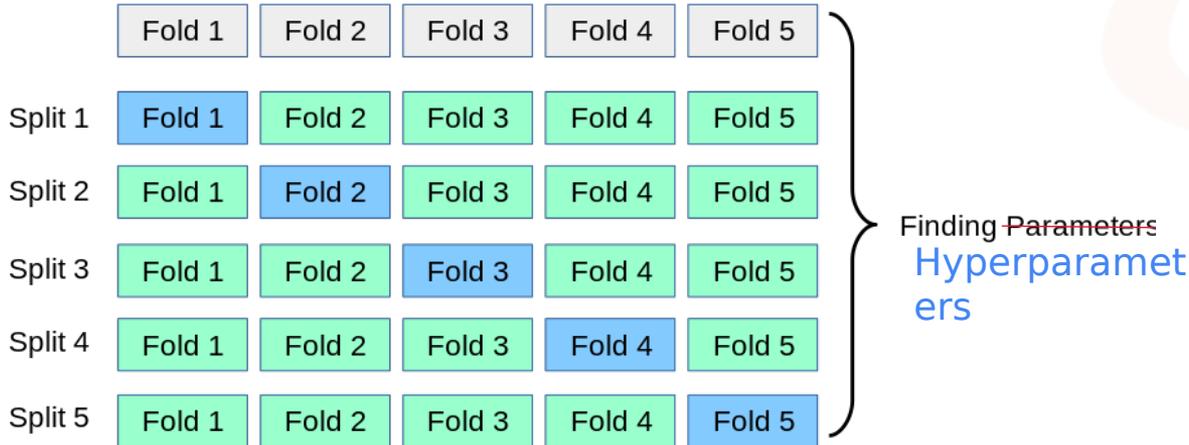
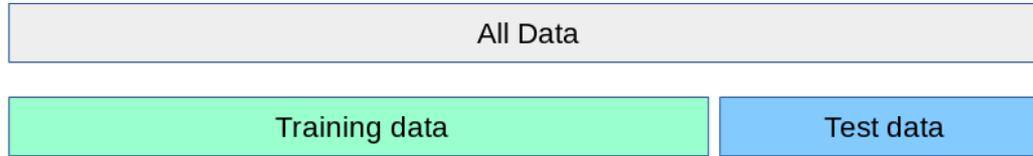
1. Using unseen **test dataset** (disjoint with the training set)
2. **Cross-validation** with  $N$  subsets (“splits” or “folds”)
3. **Leave-one-out:** cross-validation with a single example as the test set and all other examples composing the training set

Never estimate the generalization error using the training or validation sets!

# Cross-validation (CV) for model selection and evaluation



One way of using CV:



Estimate generalization error

CV can be used for estimating the generalization error and /or hyperparameters

CV can also use all data

Final model and its parameters should be obtained using all data

# Experiment reproducibility is not only initializing RNG with a given seed



Three different pseudo random number generators (RNG) when simulating with Tensorflow

```
1 import numpy as np
2 import tensorflow as tf
3 import random as python_random
4 # Start random number generation in
5 # well-defined initial state.
6 np.random.seed(123) # Numpy
7 python_random.seed(456) #Core Python
8 tf.random.set_seed(789) #Tensorflow
```

For reproducibility, one needs also to properly provide dataset and code